



| Titre: Title: | Numerica | al predictions in turbomachinery analysis | |
|-------------------------|--|---|--|
| Auteurs: Authors: | Marcelo Reggio, Ricardo Camarero, & Thi C. Vu | | |
| Date: | 1985 | | |
| Туре: | Rapport / Report | | |
| Référence: Citation: | Reggio, M., Camarero, R., & Vu, T. C. (1985). Numerical predictions in turbomachinery analysis. (Rapport technique n° EPM-RT-85-07). https://publications.polymtl.ca/10048/ | | |
| Document Open Access | | e accès dans PolyPublie in PolyPublie | |
| URL de P | URL de PolyPublie: https://publications.polymtl.ca/10048/ | | |
| | Version: | Version officielle de l'éditeur / Published version | |
| Conditions d'u | tilisation: erms of Use: | Tous droits réservés / All rights reserved | |
| | | hez l'éditeur officiel e official publisher | |
| Ir | stitution: | École Polytechnique de Montréal | |
| Numéro d | | EPM-RT-85-07 | |
| _ | RL officiel: Official URL: | | |
| | on légale: Legal notice: | | |

BIBLIOTHÈQUE

MAR 15 1985

ÉCOLE POLYTECHNIQUE

MONTREAU

EPM/RT-85-7

380-62-38

NUMERICAL PREDICTIONS IN TURBOMACHINERY ANALYSIS

Marcelo (Reggio), Ricardo (Camarero)* and (Thi)C. Vu **

- * Ecole Polytechnique de Montréal
- * * Dominion Engineering Works, Montréal

Ecole Polytechnique de Montréal Février 1985 This work was carried out with the financial support of the PRAI project #P-8122, from the NSERC of Canada and the Ministère de la Science et Technologie du Quebec, in collaboration with D.E.W.

Tous droits réservés. On ne peut reproduire ni diffuser aucune partie du présent ouvrage, sous quelque forme que ce soit, sans avoir obtenu au préalable l'autorisation écrite de l'auteur.

Dépot légal , 2° trimestre 1985
Blibliothèque nationale du Québec
Blibliothèque nationale du Canada

Pour se procurer une copie de ce document, s'adresser au:

Service de l'édition

Ecole Polytechnique de Montréal

Case Postale 6079, Succ. "A"

Montréal, Québec H3C 3A7

(514) 340-4903

Compter 0,05\$ par page(arrondir au dollar le plus près),plus 1,50\$(Canada) ou 2,50\$(étranger) pour la couverture,les frais de poste et la manutention.Régler en dollars canadiens par chèque ou mandat-poste au nom de l'Ecole Polytechnique de Montréal.Nous n'honorerons que les commandes accompagnées d'un paiement,sauf s'il y a eu entente préalable, dans le cas d'établissements d'enseignement ou d'organismes canadiens.

1. INTRODUCTION

Progress of the design process in turbomachinery demands a maximization of the power recovery while at the same time a minimization of the energy losses. The ability to respond to this kind of requirements is related to the availability of appropriate analysis tools. In this context the prediction of the physics inside a blade passage is crucial.

The objective of this report is to present a numerical time-dependent incompressible Navier-Stokes procedure to solve equations through a cascade of blades. The proposed method the primitive-variable formulation using a control volume approach. The main difficulties associated with the solution this type of problem are: the treatment of the boundary conditions on the geometries that bounds the domain, the choice a proper storage location for the dependent variables and the lack of an explicit equation for the pressure.

In the present effort the problem of the complex boundaries is treated by formulating and solving the conservation equations on a curvilinear coordinate system that matches the boundary domain. This procedure is straitghforward and universal, because the boundary nodes always coincide with the domain boundary, and no particular procedure is required at these locations.

Among the techniques that can be used to numerically create a curvilinear mesh, the body-fitted method has been adopted. Such system

proposed by Thompson[1] and incorporated on a software package devised by Garon[2] is used for the mesh generation.

effective cell structure to deal with incompressible fluid Αn flows is the staggered grid[3] formulation. This technique checkerboard pattern for and pressure fields, but velocity increases the complexity by requiring a different location together with a different computational cell for each velocity component and the pressure. In the development presented here, only one computational cell is needed, and velocity components and pressure are computed at the same location. Furthermore the good qualities of staggered mesh formulation are preserved by using an opossed the difference scheme for pressure and fluxes.

A pressure equation for a curvilinear system was derived on the basis of the SIMPLE[4] method and applied to obtain a satisfactory pressure field that meets the mass constraint requirement.

2.GOVERNING EQUATIONS

When solving the equations of motion on a curvilinear coordinate system, it seems natural to use as dependent variables velocity the components along these coordinates. In doing so the scalar equations (as continuity and energy) are in consevation law form, but not the momentum equation (a vectorial one) due to source like terms appearing as Christoffel Symbols[5]. These terms correct the momentum components of a fluid that is "constrained" to move along

a path defined by a coordinate which is not a straight line[6]. However as every mesh point belongs to a different vector basis, if the change in angle and vector basis length from grid point to grid point is severe, despite the correction, the numerical calculation could suffer.

A way to solve this problem is to keep the cartesian velocity components as the dependent variables. In this case all properties will be in the conservation law form (momentum is conserved on a straight line). The resulting system is hybrid where both cartesian and contravariant components coexist, but these equations are not significantly more complex than their cartesian counterpart, and the discrete approximations can be easily handled.

Following this approach ,the time dependent Navier-Stokes equations can be written in strong conservative form as[7]:

where:
$$\frac{\partial g}{\partial t} + \frac{\partial E}{\partial \bar{t}} + \frac{\partial F}{\partial \bar{t}} = \frac{\partial R}{\partial \bar{t}} + \frac{\partial S}{\partial \bar{\eta}}$$
 (1)

$$q = J \begin{bmatrix} 0 \\ u \\ v \end{bmatrix} \quad E = J \begin{bmatrix} u \\ uU + p\xi_x \\ vU + p\xi_y \end{bmatrix} \quad F = J \begin{bmatrix} v \\ uV + p\eta_x \\ vV + p\eta_y \end{bmatrix}$$

$$R = \mu J \begin{bmatrix} g^{11}u_{\xi} + g^{12}u_{\eta} \\ g^{11}v_{\xi} + g^{12}v_{\eta} \end{bmatrix} \quad S = \mu J \begin{bmatrix} g^{21}u_{\xi} + g^{22}u_{\eta} \\ g^{21}v_{\xi} + g^{22}v_{\eta} \end{bmatrix}$$

and μ represents the viscosity.

The contravariant velocity components U,V along the curvilinear coordinates and the cartesian velocity components u,v are related by:

$$U = u\xi_{x} + v\xi_{y}$$

$$V = u\eta_{x} + v\eta_{y}$$
(2)

The metric terms $\xi_{\times},\xi_{\gamma},\eta_{\times},\eta_{\gamma}$, the jacobian J and the contravariant metric tensor components g^{11},g^{12},g^{21} , and g^{22} are obtained from:

$$\xi_{\kappa} = y_{\eta}/J, \qquad \xi_{\nu} = -\kappa_{\eta}/J$$

$$\eta_{\kappa} = -y_{E}/J_{\eta}$$
 $\eta_{\gamma} = x_{E}/J$

$$J=x_Ey_n-x_ny_E$$

$$g^{11} = \xi_{x}^{2} + \xi_{y}^{3}$$
 $g^{12} = \xi_{x}\eta_{x} + \xi_{y}\eta_{y}$ $g^{21} = g^{12}$ $g^{22} = \eta_{x}^{2} + \eta_{y}^{3}$

3. GRID LAYOUT

The most frequent grid structure used in the numerical solution of incompressible fluid flow problems was initially introduced for cartesian geometries by Harlow and Welch [3], and is known as the staggered grid. In this arrangement the pressure is stored at the center of the cell, while the different velocity components are stored at the vertical and horizontal respectively. Although this disposition has demonstrated the ability checkerboard pattern for velocity and pressure fields to avoid a its implementation for a curvilinear system where more velocity component has to be stored on each face lead to some difficulties. As a result of this, in the present work is a different scheme and grid arrangement that preserves proposed the good properties of the staggered mesh, while alleviating the geometric complications computer implementation generally and encountered when using curvilinear coordinates.

The proposed structure stores pressure and cartesian velocity components at the center (i+1/2,j) of a computational element made up of one width in the "streamwise" coordinate direction and two units in the other.The grid cell is shown on fig.1.This computational cell is used for both mass and momentum calculations. It has to be noted that while the momentum equations involve the cartesian velocity curvilinear and components, the conservation depends only on the contravariant velocity components U and V,located at the center of the faces i,i+1 and

j-1,j+1 of the element shown on fig.(1) respectively.

4. DISCRETIZATION

Based on the above grid pattern, the equations are discretized to obtain a system of algebraic equations.

Second order differences are used to evaluate mass and pressure gradients in the η direction. The velocity values at the j+1 and j-1 faces (fig.1) are calculated by overlapping elements in that direction; while the pressure is obtained by a simple average of two neighbours points in the same direction.

In the & direction no overlapping or averaging is used, this time the treatment is done in a different manner. Mass gradients are obtained by upwind differencing, so the flux through the downwind face i+1 is controlled by the velocity at the center i+1/2,j of the element. Pressure gradients on the other hand, are calculated via downwind differences, that is to say, that the pressure located at the cell center i + 1/2,j acts on the upstream face i.

A similar treatment for the solution of the compressible Euler equations can be found in [8], and an interesting analysis of the opposed difference idea, is given in [9]. Recently Fuchs and Zhao[10] have also presented a combination of forward and backwad differences coupled with the multigrid method. References [9] and [10] solve the steady viscous equations.

The scheme is explicit and in compact form can be written as:

$$\Delta q + \Delta t (E_{E} + F_{\eta})^{\eta} = \Delta t (R_{E} + S_{\eta})^{\eta}$$
 (3)

where Δ denotes the forward time difference operator and n the time level.

4a) Continuity Equation

From this form, and from the definition of equation (1) the discrete approximation of the continuity equation with the superscript n dropped is written as:

$$\frac{(JU)_{1+1,j} - (JU)_{1,j} + (JV)_{1+1/2,j+1} - (JV)_{1+1/2,j-1}}{\Delta \xi} = 0$$
 (4)

This equation involves the contravariant velocities U and V at the cell faces (that is not the case of the cartesian components located at the cell center), and it is noted that only one component is required to calculate the mass flow through each face. For a better understanding of the way that these components are computed, some details concerning the scheme and variables storage are given.

The cartesian velocity components are calculated and stored at the center (i+1/2,j) of the computational cell with corners (i,j-1; i+1,j-1; i+1,j+1; i,j+1) (fig.1). However due to the overlapping in the j direction these properties are also known at the center of the face i+1/2,j+1, because they corrrespond to values the values of the cell center with corners (i,j;i+1,j;i+1,j+2;i,j+2) (fig.2). The same reasoning applies for the j-1 level.

With the known cartesian velocities at all j levels(due to the overlapping grid), the V components at $j \pm 1$ faces are obtained from (2) as:

$$V_{1+1/2,j\pm 1} = U_{1+1/2,j\pm 1}(\eta_{x})_{1+1/2,j\pm 1} + V_{1+1/2,j\pm 1}(\eta_{y})_{1+1/2,j\pm 1}$$
 (5)

As mentionned earlier, the cartesian velocity componets obtained from the momentum equations are computed at the center i+1/2,j of the computational cell, and are not known at the required locations

i,j and i+1,j. To calculate the required U components at such levels upwinding is used for the mass flow; and they are obtained from equation (2) as:

$$U_{i,j} = u_{i-1/2,j}(\xi_{\mathsf{N}})_{i,j} + v_{i-1/2,j}(\xi_{\mathsf{Y}})_{i,j}$$

$$(6)$$

$$U_{i+1,j} = u_{i+1/2,j}(\xi_{\mathsf{N}})_{i+1,j} + v_{i+1/2,j}(\xi_{\mathsf{Y}})_{i+1,j}$$

4b) Momentum Equations

The discrete form of the momentum equations requires the knowledge of the convected momentum fluxes and diffusion terms at the cell faces. These terms are evaluated by adopting the weighted upstream difference scheme of Raithby and Torrance[11]; for example the convected property u and the diffussion term g¹¹du/dξ at the upstream face are calculated by:

$$u_{i,j} = (1/2 + \alpha_{i,j})u_{i-1/2} + (1/2 - \alpha_{i,j})u_{i+1/2,j}$$
 (7)

and

$$C_{i,j} = g^{i}du/d\xi|_{i,j} = g_{i,j}^{i}\beta_{i,j}\frac{(u_{i+1/2,j} - u_{i-1/2})}{\Delta\xi}$$
 (8)

where α and β are coefficients depending on the Peclet number[12].

With these terms known the momentum equation written for example for the u component becomes:

$$J_{1+1/2,3}(\underline{u^{n+1}-u^n})_{1+1/2,3}$$
 Δt

- + (JuU)_{1+1,3}-(JuU)_{1,3} Δξ
- + $\frac{(JuV)_{1+1/2,3+1}-(JuV)_{1+1/2,3-1}}{2\Delta\eta}$
- + $P_{1+3/2,1}(J\xi_{\times})_{1+1,1}-P_{1+1/2,1}(J\xi_{\times})_{1,1}$ $\Delta\xi$
- $+ \frac{p_{i+1/2,j+1}(J\eta_{\times})_{i+1/2,j+1} p_{i+1/2,j-1}(J\eta_{\times})_{i+1/2,j-1}}{2\Delta\eta}$
- $+ \frac{C_{1,j} C_{1+1,j}}{\Delta \xi} + \frac{C_{1+1/2,j+1} C_{1+1/2,j-1}}{2\Delta \eta} = 0$ (9)

5. SOLUTION PROCEDURE

The algorithm starts by guessed pressure and velocity fields, from which the cartesian momentum equations are solved. Denoted by u* and v* the resulting velocity components that do not conserve mass, are then substituted into equations (5) and (6) to compute the contravariant velocity components U* and V*.

The next step, and probably the most difficult when solving incompressible flow problems is to correct the U* and V* velocities in such a manner to yield a pressure field which drives velocities that satisfy mass conservation.

The approach followed to handle the velocity-pressure coupling

problem is based on the principle of the SIMPLE[4] method. According to this technique the momentum equations are used to obtain relations between corrections to the velocity and presssure fields which violate the continuity condition.

The momentum equations are written twice, once for velocity and presssure fields that do not verify the continuity constraint, and then for fields that satisfy mass conservation.

For example the discretized x momentum equation is written for a u* and p*'s that violate mass conservation as:

$$u^{+}T^{\pm}I_{/2,,j} = u^{+}T_{+1/2,,j} + \Delta t \left\{ p^{+}_{1+1/2,,j} (J\xi_{\times})_{1,,j} - p^{+}_{1+3/2,,j} (J\xi_{\times})_{1+1,,j} - \frac{1}{\Delta \xi} \right\}$$

$$\frac{p_{1+1/2,j+1}^{*}(J\eta_{\kappa})_{1+1/2,j+1}-p_{1+1/2,j-1}^{*}(J\eta_{\kappa})_{1+1/2,j-1}}{2\Delta\eta}$$

where FLUX and VISC represents the resulting convected and viscous terms over the element respectively.

In the same manner the equation for a velocity u and a pressure $p=p^*+\delta p$ that meets the mass constraint requirement is written as:

$$\frac{p_{1+1/2,\,j+1}(J\eta_{\aleph})_{\,1+1/2,\,j+1}-p_{1+1/2,\,j-1}(J\eta_{\aleph})_{\,1+1/2,\,j-1}}{2\Delta\eta}$$

substracting (10) from (11) one obtains:

$$\delta u = (u-u^{*})_{\uparrow \uparrow \uparrow /2, j} = \Delta t \{\delta p_{i+1/2, j}(J\xi_{x})_{i, j} - \delta p_{i+3/2, j}(J\xi_{x})_{i+1, j} - \Delta \xi$$

$$\frac{\delta p_{i+1/2,j+1}(J\eta_{\varkappa})_{i+1/2,j+1}-\delta p_{i+1/2,j-1}(J\eta_{\varkappa})_{i+1/2,j-1}\}}{2\Delta \eta} \tag{12}$$

Following the same procedure a similar equation for the $\ensuremath{\mathsf{v}}$ component can be found.

With this cartesian velocity corrections $\delta u=u-u*$ and $\delta v=v-v*$ known, the corresponding expressions for the curvilinear velocity corrections $\delta V=U-U*$ and $\delta V=V-V*$ are found by using analogous expressions to relations (2), that is:

(13)

$$\delta V = \delta u \eta_{\times} + \delta v \eta_{>}$$

Equations (13) depends on the pressure corrections &p, so a relation to obtain these correction is needed. This is achieved by using the continuity equation written in terms of velocity components U,V and U*,V* that do and do not satisfy mass conservation respectively, the discrete form of the latter is written as:

$$\frac{(JU^{*})_{1+1,3} - (JU^{*})_{1,3}}{\Delta \xi} + \frac{(JV^{*})_{1+1/2,3+1} - (JV^{*})_{1+1/2,3-1}}{2\Delta \eta} = D$$
(14)

where D depends represents a mass source term. Substraction of (14) from (4) gives:

$$\frac{(J\delta U^*)_{1+1,j} - (J\delta U^*)_{1,j} + (J\delta V^*)_{1+1/2,j+1} - (J\delta V^*)_{1+1/2,j-1}}{\Delta \xi} = -D$$

(15)

This equation involves 9 pressure points, however if only the pressure correction at the center i+1/2, j of the element is retained, while the effect of the neighbouring pressures is neglected

one obtains a definitive equation for the pressure change

$$\delta p_{1+1/2,j} = fP(\delta U, \delta V, D)$$

In the present approach the pressure adjustement is done cell by cell as in the MAC method[13].

Once on is evaluated at the cell center, the curvilinear velocity corrections of and of are calculated, then all corrections combined with the inexact velocity and pressure fields in order to verify the mass constraint; that is:

$$U = U^* + \delta U$$

 $V = V^* + \delta V$ (16)
 $p = p^* + \delta p$

To modify the variables over the entire computational domain the grid is swept point-by-point in the inlet-outlet direction. Improved values are inmediately used as the procedure advances. This procedure is repeated until all cells have D values less than a desired level of accuracy.

When the above step is completed,only one curvilinear

velocity component that meets the mass constraint requirement is known on each face (U and V on the η and ξ faces respectively). To obtain the "missing" component averaging of surrounding velocities that satisfy continuity is used[12]. Then the cartesian velocity components are decoded an the boundary conditions applied.

Finally the time level is advanced and the cycle repeated until the steady state is reached.

6. APPLICATIONS

6.1 Cascade Analysis

In order to analyse the predictions features of the present model, a first application to turbomachinery was carried out by computing the flow on a NACA[14] cascade. The discretisation employed 90x27 grid points and several tests up to Re=20,000 were conducted and for an angle of attack of 30°.

The computational grid for this case is given in fig.3 where the blade-to-blade passage is shown to illustrate the grid distribution.

Figure 4. illustrates the velocity field obtained for Re=2000, while fig.5 shows the calculated S coefficient (defined as S = $1-C_p$) compared with the experimental values (Ref.14) The over all agreement is good, in particular the peak pressure at the leading edge is

well captured together with a good simulation of the diffusion flow on the suction side. However the trailing edge prediction shows some discrepancy.

A comparison of the computed aerodynamics parameters, such lift and drag coefficients, outlet angle and losses, has been carried out with the experimental data of Ref [14] and the results presented on table 1.It can be appreciated that the outlet angle and the lift coefficient are reasonably well predicted for all Reynolds numbers, however the drag coefficient is much higher than the experimental value. This can be attributed to the intrinsic numerical the discretization process; a similar viscosity arising from phenomenon was also found in a finite element solution on the geometry [15].

A second cascade test was done on a blade passage reported by Langston et al.[16]. The experimental data presented by these authors is for a three-dimensional experience, however due to the constant cross section it is reasonable to attempt a comparison with the data reported at the midspan of the channel.

shows the calculated (using 48x19 mesh points and for Re=1000) and experimental static pressure coefficient on the blade surface. The pressure side shows a good agreement of values and the overall trend is well predicted. On the suction side the pressure distribution quantitative disagreement presents some near the minimun.This can be attributed to the absence of secondary flow movement perceived in the three-dimensional

flow[17]; in spite of that the trailing edge pressure distribution is well predicted

Table 2. shows the calculated aerodynamic parameters for Re=1000 and Re=5000, and the available experimental data. As in the previous case and for the same reason, the numerical value of the aerodynamic loss is greater than the experimental, in spite of that, the computed outlet angle conforms very well the measured value given in [16].

After these basic verifications completed a more complex application to turbomachinery was attempted by studying the flow through two blade passages one after the other. This kind of configuration found on the spiral casing of the hydraulics turbines is formed by the stay vane and the wicket gate. The first passage is static while the second is of variable angle. A general view of the forementionned geometry is given in fig. 7.

A representative illustration of the passage form is shown on fig.8, and a typical body-fitted mesh used to predict the flow on this sort of problem is depicted on fig.9.

The flow through these two cascades in series was fully tested for differents angles of attack of the wicket gate and for different Reynolds numbers, this latter defined in terms of the throat radius.

Figure 10 presents the velocity field obtained on a characteristic channel. For this example the Reynolds number is of 10,000, the stay vane angle is of 34.5°, the wicket angle of 33.°, and

the inlet and outlet flow angles of 20° and 37.96°respectively.

This general representation allows to visualize particular regions of interest, such as the zone nearby the trailing edge of the stay vane and the leading edge of the wicket gate, where the flow undergoes rapid changes.

The skin friction coefficient calculated on the surfaces of the blades is displayed as function of the noramalized cord(Fig.11)The full line is used to indicate the wicket gate and the dotted for the stay vane, arrows represent the suction side. This kind of information is quite useful in the design process; in particular it is noted that when the skin friction coefficient becomes negative reverse flow and separation occurs.

In the same way that in the previous diagram, fig.12 represents the S coefficient as function of the cord. Because the purpose of the forementionned blades is not to produce lift but to induce the flow, the kowlowedge of this variable is useful to minimize the area between the pressure and suction side curves.

As mentionned earlier several tests for different attack angles of the wicket gate were conducted in the diffuser passage. The information obtained from these tests was then used to build a plot where isocontours of energy losses are displayed as function of wicket gate opening and attack angle. This information is illustrated on fig. 13 from which it can be appreciated for example, that for the first ten degrees of variation of the attack angle (from 20° to 30°),

the energy losses change is considerable; while that for the last ten degrees(between 50° and 60°) this variation is minimal.

A further study was done by performing a quasi-3d analysis on a Kaplan turbine. On fig.14 a representation on the Z-R plane of the mesh and the potential flow path, including the intake, runner and draft tube is presented. Figure 15 shows a partial view of the set of blades (for sake of clarity only some of them are drawn) where the numbers are to indicate the sections that are developed to work out 2-D investigations.

Figures 16 and 17 illustrate the resulting developed blade profile on sections 2 and 5. Computations were done for these and for the remaining sections (3 and 4) using 90x27 grid points for Re=10,000 and where differents angles of attack are imposed on each blade-to-blade portion. The obtained velocity fields for the levels of figs. 16 and 17 are drawn on figs. 18 and 19. The corresponding calculated pressure coefficient is depicted as a function of the nondimensional cord on figs. 20 and 21.

A comparison of the results obtained from the quasi-3D analysis with the available experimental data has been done and is illustrated on fig. 22 .In this picture the tangential velocity components for the different levels are drawn as function of the radius and the nondimensional speed ratio \S (\S = $u_{abs}/N2gH$, where u_{abs} represents the absolute tangential velocity, g the gravity constant and H the head).The concordance of numerical and experimental values is very good for the inner sections, however some disparity is observed for the

outer levels.

A procedure to solve incompressible flows on arbitrary shapes without using a staggered formulation has been developed. This is accomplished by the use of an opposed-difference scheme. Applications to compute the flow through cascades have been done. The reported results are satisfactory and show that the proposed method is a plausible tool for turbomachinery analysis.

REFERENCES:

- 1. R.Camarero and M.Younis , Efficient Generation of Body-Fitted Coordinates for Cascades using Multigrid , AIAA Journal vol 18, pp. 487-488 ,1980
- 2. A. Garon, and R. Camarero, Interactive Turbomachinery Design, NUMETA 85, International Conference Series on Advances in Numerical Methods in Engineering: Theory and Applications, University College, Swansea, January 7-11, 1985
- 3. F.H Harlow and J.E. Welch, Numerical Calculation of Time Dependent Viscous Incompressible Flow of Fluid with Free Surface, Phys.Fluids, Vol. 8, no 12, pp 2182-2189,1965
- 4. S.V. Patankar, Numerical Heat Transfer and Fluid Flow Hemisphere, Washington., 1980
- 5. P.R Eisman and P. Stone, Conservation Laws of Fluids Dynamics -A Survey, SIAM Review, vol 22 pp.12-27,1980
- 6. D. Schnack and J. Killeen, Nonlinear, Two-Dimensional Magnetohydrodynamic Calculations, Journal of Computational Physics, vol.35, pp110-145, 1980

- 7. R. Peyret and H. Viviand, Computation of Viscous Compressible Flow Based on the Navier-Stokes Equation, North Atlantic Treaty Organization, AGARD 212 , 1975
- 8. J.D Denton, A Time Marching Method for Two and Three Dimensional Blade-to-Blade Flows, A.R.C., REM 3775, 1975
- 9. D.F Roscoe, The Numerical Solution of the Navier-Stokes Equations for Three-Dimensional Laminar Flow in Curved Pipes using Finite Differences Methods, J. of Engineering Mathematics, vol 12, pp 303-323,1978
- 10. Fuchs, L. and Zhao H-S., Solution of Three-Dimensional Viscous Incompressible Flow By A Multigrid Method, Int. Journal for Numerical Methods in Fluids, vol. 4 ,pp 539-555, 1984
- 11. G.D Raitby and K.E Torrance, Upstream Weighted Differencing Schemes and their Application to Elliptic Problems Involving Fluid Flows, Computer Fluids vol. 2, pp 191-206, 1974
- 12. C.R Maliska, A Solution Method for Three-Dimensional Parabolic Fluid Flow Problems in Nonorthogonal Coordinates", Ph. D. Thesis, University of Waterloo, Canada, 1981
- 13. C.W Hirt, B.D Nichols and N.C Romero, SOLA- A Numerical Solution Algorithm for Transient Fluid Flows, 1975, Los Alamos Scientific Labortory, Report LA-5852, 1975

- 14. J.C. Dunavant and J.R Erwin, Investigation of a Related Series of a Turbine-Blade Profiles in a Cascade, NACA T.R. Note 3802, 1956
- 15. A. Fortin ,R. Camarero , T. C. Vu, and M. Fortin, Simulation Numérique d'Ecoulements Visqueux dans une Turbine Hydraulique,Rapport Technique, Ecole Polytechnique de Montréal,1985
- 16. L.S. Langston, M.L. Nice and R.M. Hooper, Three-Dimensional Flow Within a Turbine Cascade Passage, ASME Journal of Enginneering for Power, vol. 99 no. 1 pp. 21-28, 1977
- 17. C. Hah, A Navier-Stokes Analysis of Three-Dimensional Turbulent Flows Inside Turbine Blade Rows at Desing and Off-Desing Conditions, ASME Paper 83-GT-40

TABLE 1

Comparison of experimental (Ref. 14) and computed values

| | Re= 50 | Re= 1000 | Re=20,000 | Experimental |
|---------------------------|--------|----------|-----------|---------------|
| $\mathbb{C}_{\mathbf{D}}$ | 1.33 | 0.38 | 0.23 | 0.04 |
| CL | 1.46 | 1.41 | 1.36 | 1.6 |
| Losses | 125% | 42% | 28% | dian dian saw |
| outlet angle | 43.2 | 41.3 | 38 | 42.6 |

TABLE 2

Comparison of experimental (Ref. 16) and computed values

| | Re= 1,000 | Re= 5,000 | Experimemtal |
|-----------------|-----------|-----------|--|
| C _D | 2.03 | 1.70 | |
| C _L | 2.74 | 2.72 | Name and the second sec |
| Losses | 135% | 135% | 25% |
| outlet angle | 64.4 | 63.5 | 64 |

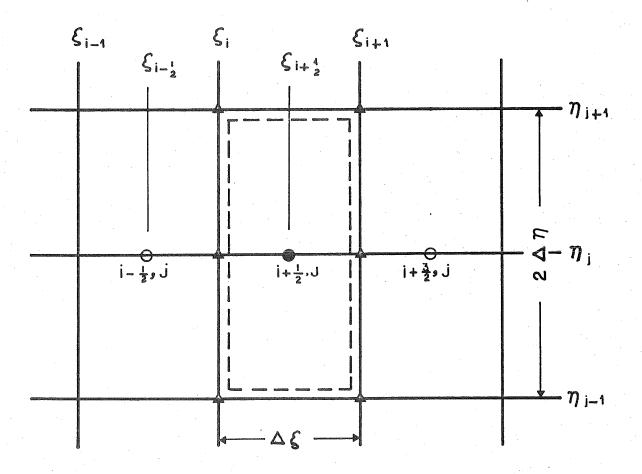


Fig. 1 Basic Computational Cell

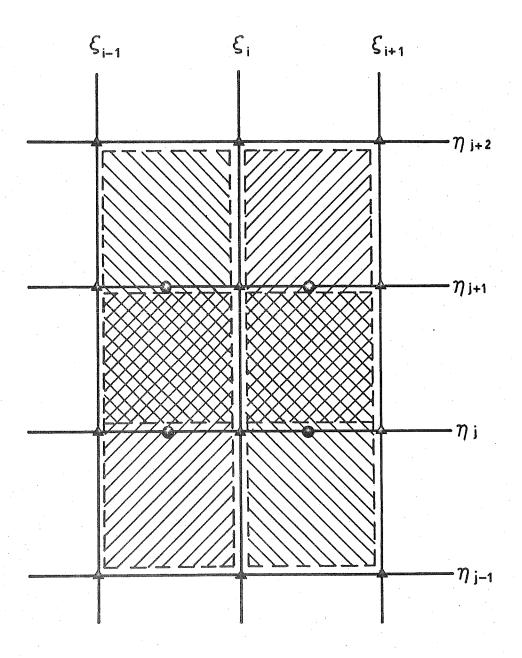


Fig. 2 Overlapping Grid

CARACTERISTIQUES DU PROFIL

| PROFIL | | | 2 | C5Ø.PR0 |
|--------|----|-----|----|---------|
| CORDE | | | 22 | 1.000 |
| NOMBRE | DE | PTS | = | 30 |

CARACTERISTICUES DE LA CASCADE

| CANAC | E41311 | 4ULU . | <i>-</i> | | -50 |
|-------------------------|--|--------------|-------------|----------------------|------|
| NO. TO | DE RAN DIAL COL DL. ENTE DL. SORT | LONNE REE | 153 | 27 92 32 32 | |
| LONG. LONG. LONG. | INTERAL ENTREE SORTIE | | 2 E E | Ø . 61 1 . 1 | |
| ANGLE | ENTREE PROFIL SORTIE | IDEG IDEG |) = | 30 - 25 - 40 | , 20 |
| CONC. | RANGEES COL EN | | = | Ø . 61 Ø . 31 | |

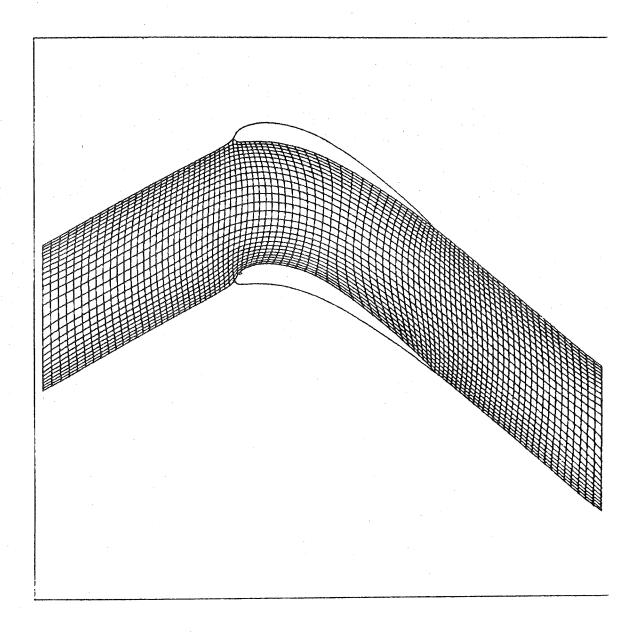


Fig. 3 Body-Fitted Grid for the Cascade of Ref. (14)

ANALYSE DJF - NACA90 SOLUTION R2000.056 ECOULEMENT VISOUEUX REYNOLDS = 2000.0 ANGLE PROFIL = -25.00 ANGLE ATTAQUE = 30.00 ANGLE FUITE = -39.98 COEF. CD = 0.3168 COEF. CL = 1.397 COEF. CA = 0.4371 COEF. CT = 1.364 TORQUE CM = -1.385

CARACTERISTIQUES DU PROFIL

PROF 11 = C50 PRO CORDE = 1.000 NOMBRE DE PTS = 30

CARACTERISTIQUES DE LA CASCADE

| CARACTERISTIONES DE | LA CASCADE |
|--|---------------------------|
| CASCADE NOMBRE DE RANGEE = NO. TOTAL COLONNE = NO. COL. ENTREE = NO. COL. SORTIE = | 27 86 28 |
| LONG INTERAUBE = LONG ENTREE = LONG SORTIE = | 1.000 |
| ANGLE PROFIL (DEG) = | 30.00 -25.00 -40.00 |
| CONC. RANGEES = CONC. COL. ENTREE = | |



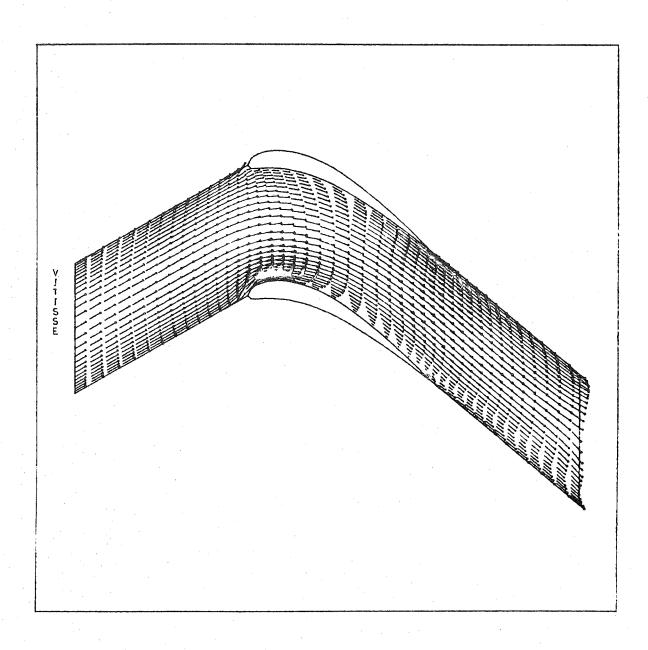
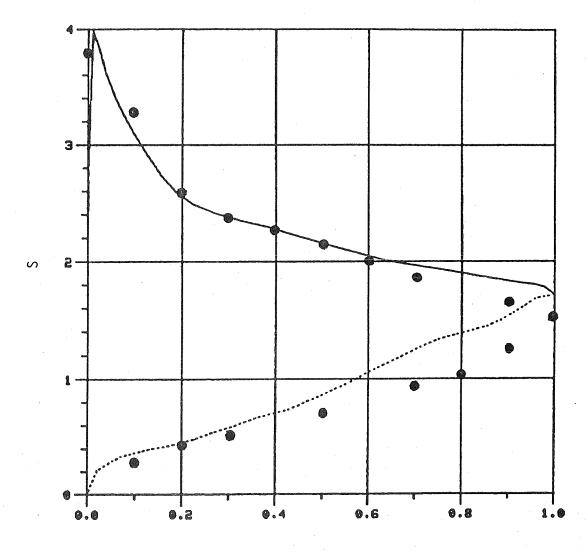


Fig. 4 Velocity field for Re = 2000



Axial Cord

Fig. 5 Calculated and Experimental (represented by dotes) coefficient for the profile of Ref. 14

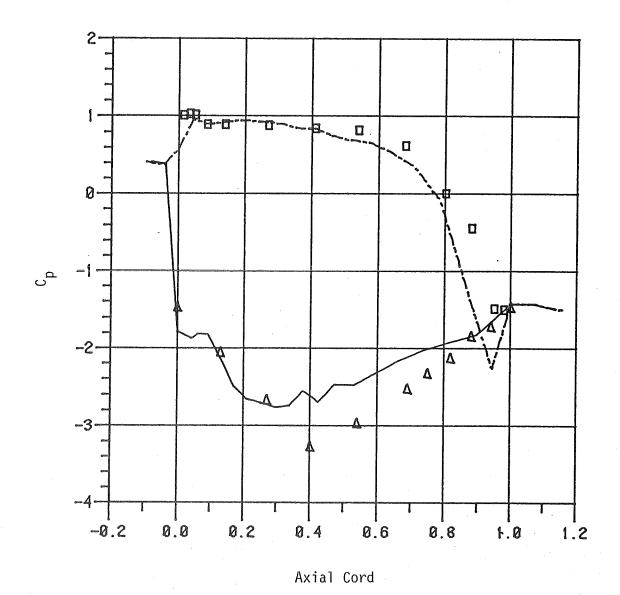


Fig. 6 Calculated and Experimental (represented by triangles and squares) pressure coefficient for the profile of Ref. 16

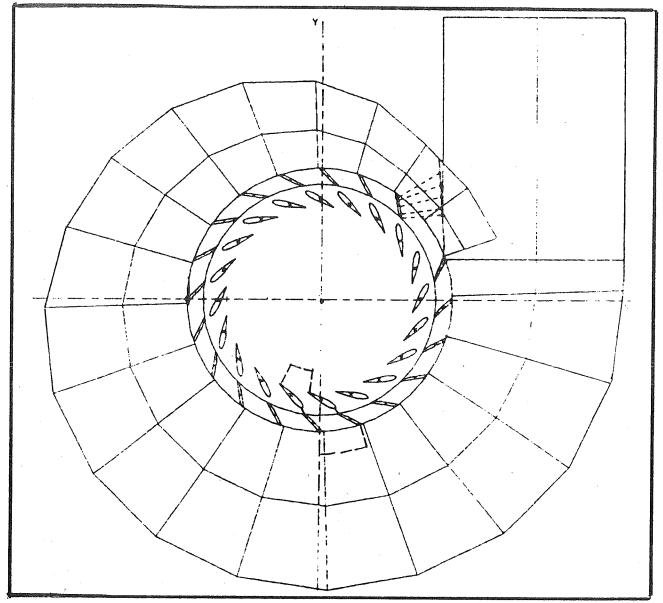


Fig. 7 SPIRAL CASING PLAN VIEW

| CARACTERISTIQUES I | DE LA CASCADE | |
|---|------------------------------|-------------------------------------|
| CASCADE YOMBRE DE RANGEE YO.TOTAL COLONNE | - A3533.CA6 - 27 - 141 | 3 |
| RAYON DE GORGE ANGLE PERIODIQUE | - 79.00 - 18.60 | (1.00) (DEG) |
| LOC.RAD. DU PIVOT LOC.ANG. DU PIVOT (P/R BORD FUITE 1 | • 7.2S | (1.11) (DEG) |
| PROFIL1 LOC.RAD.BORD ATTAC LOC.RAD.BORD FUITE CORDE ANGLE PROFIL 1 YOMBRE DE PTS | - 104.3 | (1.54) (1.32) (0.34) (DEG) |
| PROFIL2 LOC.RAD.BORD ATTAG LOC.RAD.BORD FUITE CORDE WHGLE PROFIL 2 VOMBRE DE PTS | | (1.28) (1.02) (0.42) (DEG) |
| Long. Entree Wale entree | • 25.00 • 35.00 | (0.32) (DEG) |
| LONG. SORTIE NIGLE SORTIE | - 35.00 - 45.00 | (0.44) (DEG) |
| NO. COL. ENTREE NO. COL. INTER NO. COL. SORTIE | • 25 • 5 • 35 | |
| CONC. RANGEES CONC. COL. ENTREE CONC. COL. INTER CONC. COL. SORTIE | 9.69 9.30 9.10 9.39 | |

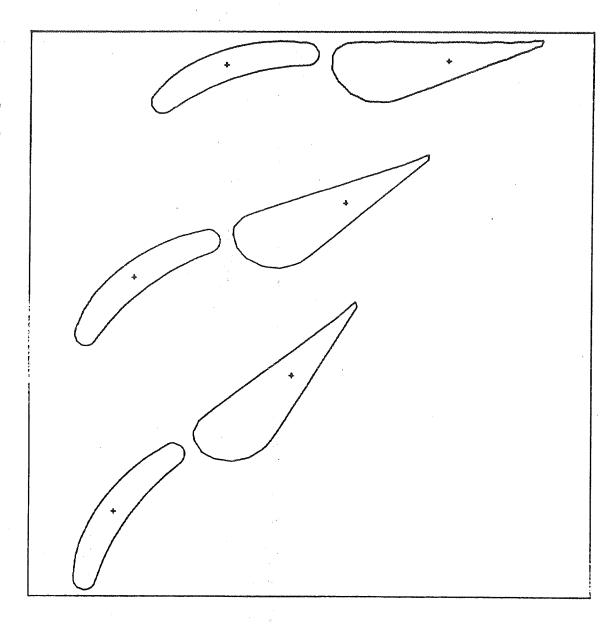


Fig. 8 Consecutive Cascades

| :MACTERISTIQUES DE | LA CASCADE | |
|--|------------------------------|-------------------------------------|
| CASCADE WATERE DE RANGEE NO. TOTAL COLONNE | a3533.cas 27 141 | |
| MAYON DE GONGE . MGLE PERIODIQUE . | 79.00 18.00 | (1.00) (DEG) |
| LOC.RAD. DU PIVOT . LOC.ANG. DU PIVOT . (P/R BORD FUITE 1) | 88. 00 7.25 | (1.11) (DEG) |
| MOFILI LOC.RAD.BORD ATTAGE LOC.RAD.BORD FUITE- CORDE ANGLE PROFIL 1 NOMBRE DE PTS | 121.8 | (1.54) (1.32) (0.34) (DEG) |
| PROFIL2 LOC.RAD.BORD ATTAGLOC.RAD.BORD FUITE- CORDE WAGLE PROFIL 2 VOMBRE DE PTS | | (1.28) (1.02) (0.42) (DEG) |
| LONG. ENTREE | 25.00 35.00 | (0.32) (DEG) |
| LONG. SORTIE . | 35.00 45.00 | (0.44) (DEG) |
| TO. COL. ENTREE . TO. COL. INTER . TO. COL. SORTIE . | 25 5 35 | |
| CONC. RANGEES COL. ENTREE CONC. COL. INTER CONC. COL. SORTIE | 0.60 0.30 0.10 0.30 | |

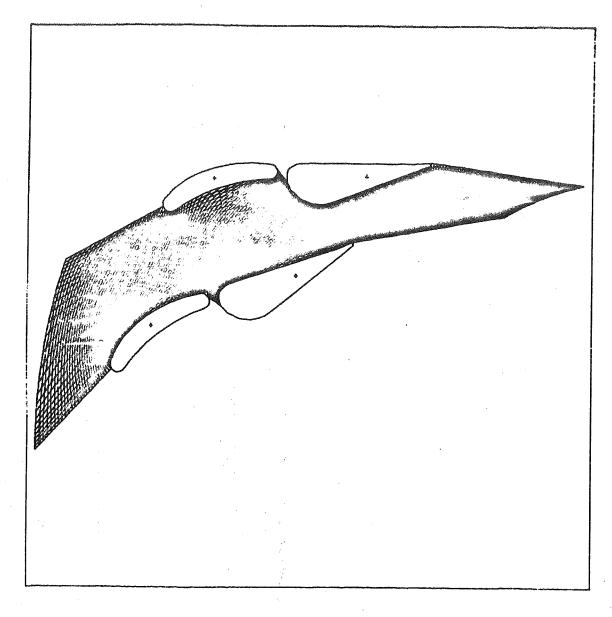


Fig. 9 Body-Fitted Mesh for Two Consecutive Cascades

ISLE MALIGNE - SYM. UGT OLUTION F3533.A38 COULEMENT UISQUEUX EYNOLDS . 10000. NGLE ATTAQUE = 30.00 NGLE FUITE = 27.82 ARACTERISTIQUES DE LA CASCADE OMBRE DE RANGEE = 27 O.TOTAL COLONNE = 143 AYON DE GORGE (1.00)NGLE PERIODIQUE = (DEG) 18.00 OC.RAD. DU PIVOT = OC.ANG. DU PIVOT = P/R BORD FUITE 1) (1.11)(DEG) OC.RAD.BORD ATTAG-121.8 (1.54)(1.32) (0.34) OC.RAD.BORD FUITE-104.3 ORDE 27.22 NGLE PROFIL 1 (DEG) 34.50 OMBRE DE PTS UKGLPR.PRO ROFILZ OC.RAD.BORD ATTAG 96.70 (1.22)OC.RAD.BORD FUITE 81.05 (1.03)28.88 (0.37) NGLE PROFIL 2 33.00 (DEG) OMBRE DE PTS 41 ONG. ENTREE (0.32) NGLE ENTREE 35.00 ONG. SORTIE 40.00 (0.51)NGLE SORTIE 45.00 (DEG) O. COL. ENTREE 25 7 O. COL. INTER O. COL. SORTIE 35 ONC. RANGEES ONC. COL. ENTREE = ONC. COL. INTER = ONC. COL. SORTIE = 0.30 0.10 0.30 OMPOSANT UX MAX -3.397 RANG= 2 .COL.=142) OMPOSANT UX MIN = -0.4660 RANG. 3 ,COL. 60)

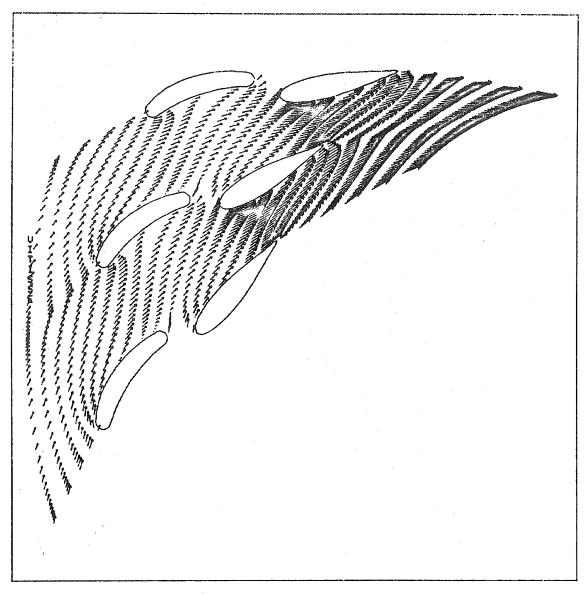


Fig. 10 Velocity Field for Two Successive Cascades

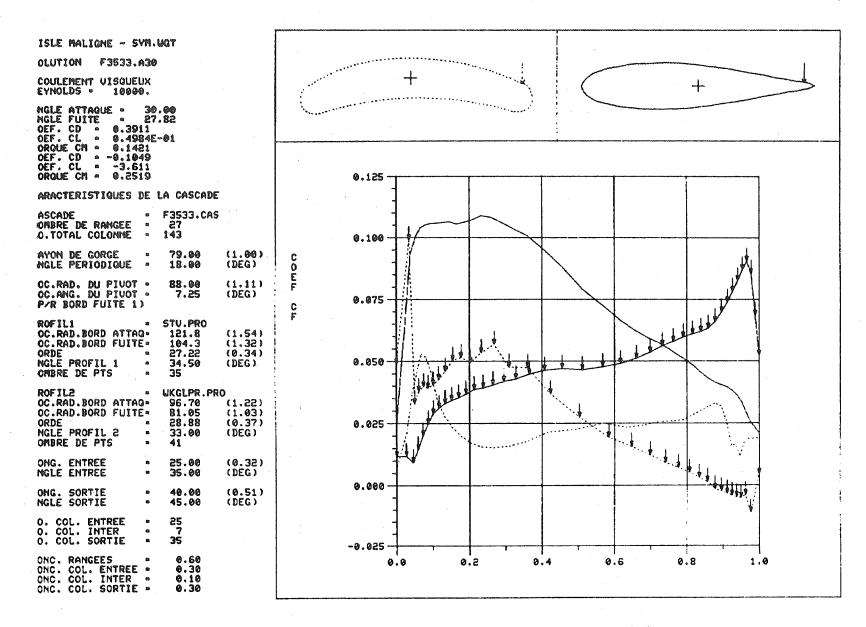


Fig. 11 Skin Friction Coefficient as Function of the Normalized Length

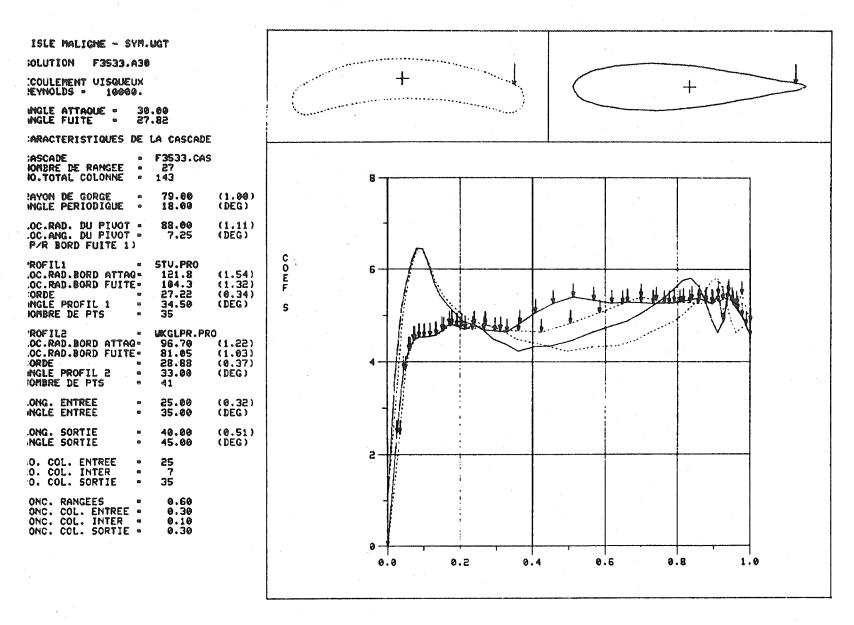


Fig. 12 S Coefficient as Function of the Normalized Length

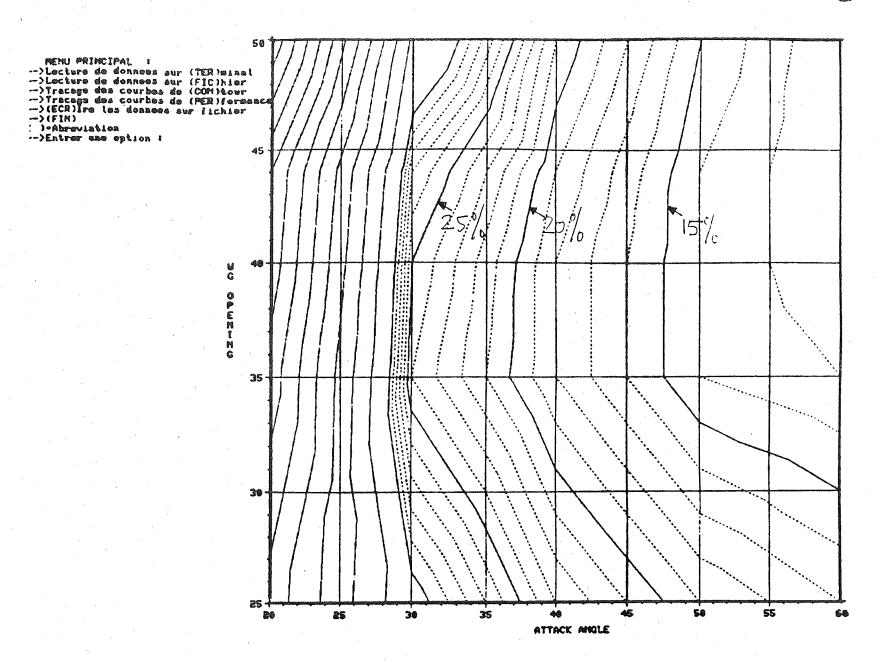


Fig. 13 Isocontours of Energy Losses

K-349 A-3.0 THROUGHFLOW SURFACE 1

PAUSE FOR COPY

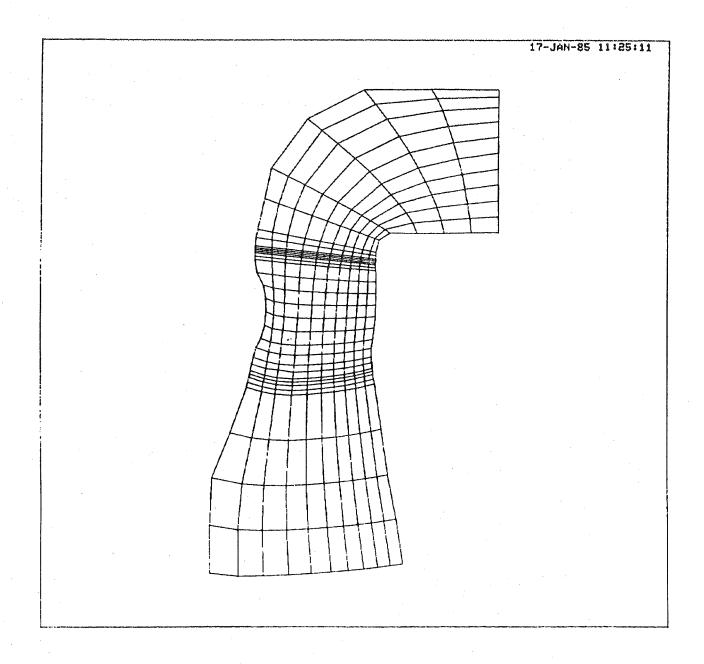


Fig. 14 Throughflow Grid for a Kaplan Runner on the Z-R Plane

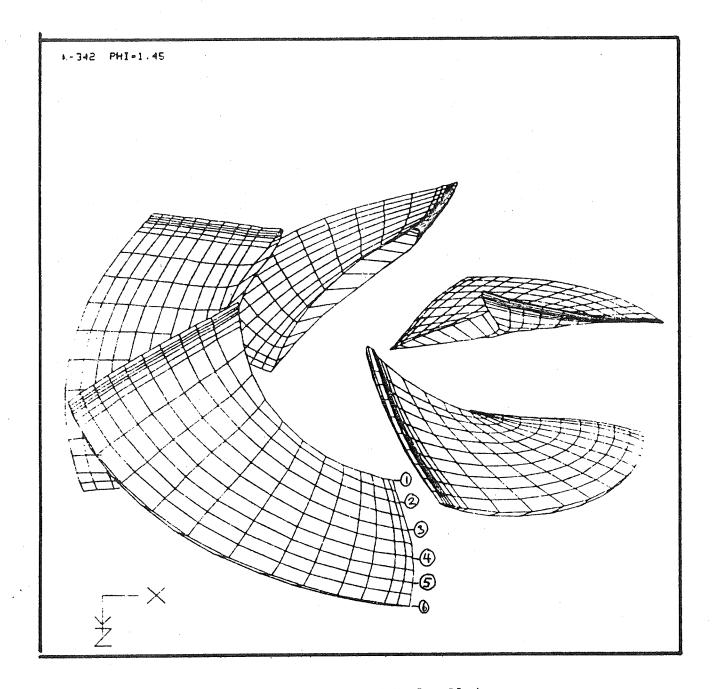


Fig. 15 3-D View of Kaplan Blades

HTERPOLATION LINEASIE

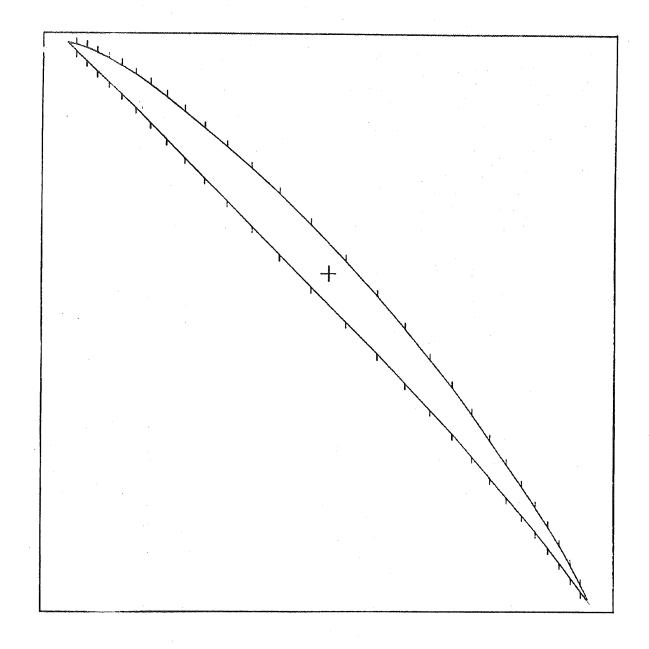


Fig. 16 Developped Profile of Section 2

:ARACTERISTIQUES DU PROFIL

| ORDE WARE DE POINT | 10 | 2 | .00 |
|-----------------------|----------|----|--------------|
| EXTRADOS INTRADOS | a 2 | | 30 30 |
| ACTEUR CONC. | 6 | 0. | S 0 |
| 4146 1141 5 ALL | n -0. | | . 0 26444 |
| (MTERPOLATION L | INE | AI | RE |

```
INTERPOLATION LINEAIRE

INTERPOLATION DU PROFIL
->(FIN)
->(INI)TIALISATION
->(LIR)E
->(ECR)IRE
->(INT)ERPOLATION
->(GRA)PHISME
->( "-ABREVIATION
INTRER UNE OPTION,...
ECR
ECPIPE LE ROM du fichier
a ecpire.
SECS.PRO
INTERPOLATION DU PROFIL
->(FIN)
->(INI)TIALISATION
->(LIR)E
->(ECR)IRE
->(INT)ERPOLATION
->(GRA)PHISME
->( "ABREVIATION
INTRER UNE OPTION,...
ENTRER UNE OPTION,...
```

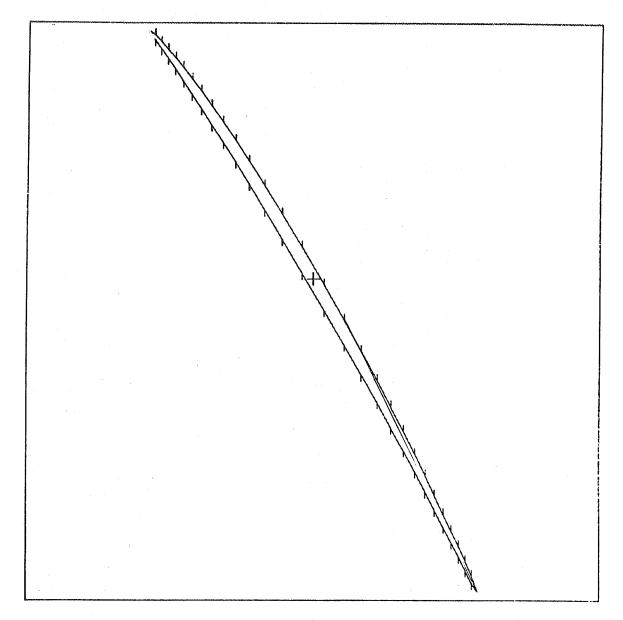


Fig. 17 Developped Profile of Section 5

MAL :: CE 1:349-SEC2 CLUTION SECZ.RES COULEMENT "ISOUEUX ENNULDS . 10000. INGLE PROFIL = -47.00 INGLE ATTAQUE = -32.93 INGLE FUITE = -51.68

OEF. CD = 0.1135 OEF. CL = 1.132 OEF. CA = 0.8461 OEF. CT = 0.7612 ORQUE CM = -0.6707

ARACTERISTIQUES DU PROFIL

'ROFIL : ORDE : IOMBRE DE PTS : SEC2.PRO 1.000 30

DE

| :ARACTERISTIQUES DE | LA CASCAI |
|---------------------|-----------|
| ASCADE | SEC2.CAS |
| IOMBRE DE RANGEE . | 27 |
| IO. TOTAL COLONNE : | |
| IO. COL. ENTREE . | |
| W. COL. SORTIE . | 35 |
| ONG. INTERAUBE . | 0.8080 |
| ONG. ENTREE . | 0.8000 |
| .ONG. SORTIE . | 1.200 |
| MGLE ENTREE (DEG)= | -33.00 |
| MGLE PROFIL (DEG). | -47.00 |
| MGLE SORTIE (DEG)= | -47.00 |
| ONC. RANGEES | 0.6000 |
| ONC. COL. ENTREE . | 0.3000 |
| ONC. COL. SORTIE . | 0.3000 |
| OMPOSANT UX MAX . | 1.222 |
| RANG. 4 ,COL.=29) | |
| OMPOSANT UX MIN = | 0.4827 |
| RANG- 2 ,COL54) | |
| | |

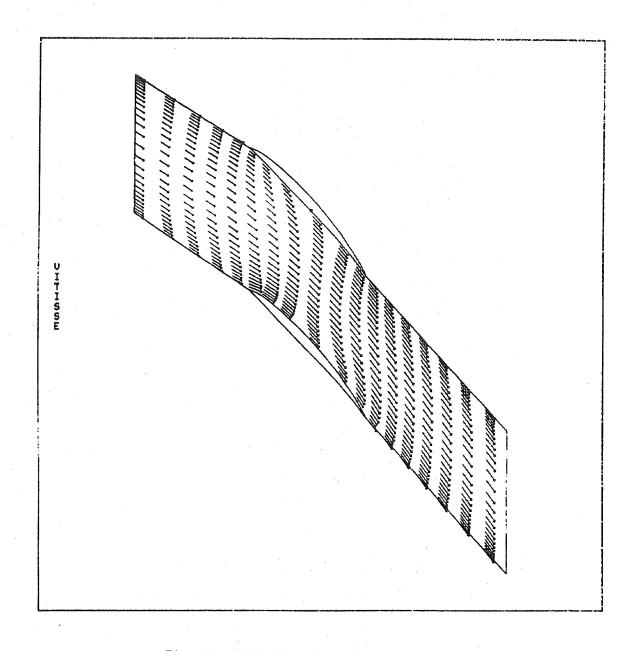


Fig. 18 Velocity Field in Section 2

NALYSE K349-8ECS OLUTION SECS.REM COULEMENT VISQUEUX EYNOLDS • 19000.

HGLE PROFIL - -60.00
HGLE ATTAQUE - -57.34
HGLE FUITE - -61.96

OEF. CD • 0.5536E-01 OEF. CL • 0.4787 OEF. CA • 0.4410 OEF. CT • 0.1941 ORQUE CM • -0.9366

ARACTERISTIQUES DU PROFIL

ROFIL = SEC4.PRO
ORDE = 1.000
OMBRE DE PTS = 30

ARACTERISTIQUES DE LA CASCADE

ASCADE - SECS.CAM
OMBRE DE RANGEE - 27
O. TOTAL COLONNE - 90
O. COL. ENTREE - 25
O. COL. SORTIE - 35

ONG. INTERAUBE • 1.138 ONG. ENTREE • 9.8809 ONG. SORTIE • 1.269

NGLE ENTREE (DEG) - -57.50
NGLE PROFIL (DEG) - -60.00
NGLE SORTIE (DEG) - -60.00

ONC. RANGEES = 0.6000 ONC. COL. ENTREE = 0.3000 ONC. COL. SORTIE = 0.3000

OMPOSANT UX MAX = 0.7603 RANG= 2 ,COL.=30) OMPOSANT UX MIN = 0.2645 RANG= 2 ,COL.=54)

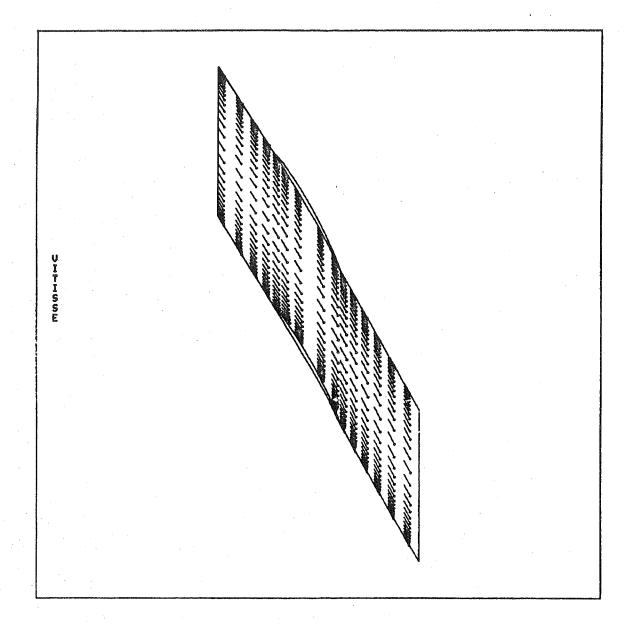


Fig. 19 Velocity Field in Section 5

Walyse K349-Sec2

DLUTION SECR.RES

COULEMENT UISQUEUX EYNOLDS . 10000.

YGLE PROFIL - -47.00 YGLE ATTAQUE - -32.93 YGLE FUITE - -51.68

DEF. CD = 0.1135 DEF. CL = 1.132 DEF. CA = 0.8461 DEF. CT = 0.7612 DRQUE CM = -0.6707

ARACTERISTIQUES DU PROFIL

ROFIL SECZ.PRO DRDE 1.000 1.000 30

ARACTERISTIQUES DE LA CASCADE

ASCADE SEC2.CAS
OMBRE DE RANGEE SEC2.CAS
O. TOTAL COLOMNE SO
O. COL. ENTREE SES
O. COL. SORTIE SEC2.CAS

NG. INTERAUBE - 0.8089 NG. ENTRZE - 0.8000 NG. SORTIE - 1.200

YGLE ENTREE (DEG)= -33.00 YGLE PROFIL (DEG)= -47.00 YGLE SORTIE (DEG)= -47.00

ONC. RANGEES - 0.6000
ONC. COL. ENTREE - 0.3000
ONC. COL. SORTIE - 0.3000

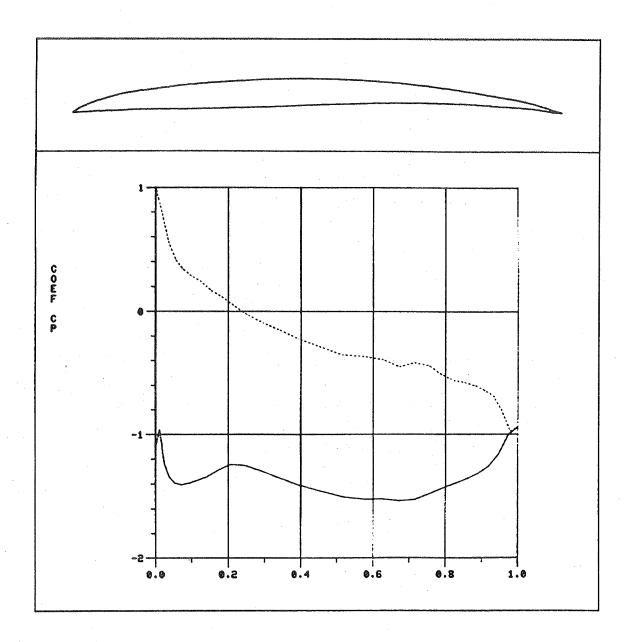


Fig. 20 Pressure Coefficient on Section 5

MALYSE K349-SECS

OLUTION SECS. REH

COULEMENT VISQUEUX EYNOLDS - 10000.

NGLE PROFIL - -60.00 NGLE ATTAQUE - -57.34 NGLE FUITE - -61.96

OEF. CD = 0.5536E-01 OEF. CL = 0.4787 OEF. CA = 0.4410 OEF. CT = 0.1941 ORQUE CH = -0.9366

ARACTERISTIQUES DU PROFIL

ROFIL - SEC4.PRO
ORDE - 1.000
OMBRE DE PTS - 30

ARACTERISTIQUES DE LA CASCADE

ASCADE SCS.CAM
ONBRE DE RANGEE 27
O. TOTAL COLONNE 99
O. COL. ENTREE 25
O. COL. SORTIE 35

ONG. INTERAUBE • 1.138 ONG. ENTREE • 0.8000 ONG. SORTIE • 1.200

NGLE ENTREE (DEG) - -57.50 NGLE PROFIL (DEG) - -60.00 NGLE SORTIE (DEG) - -60.00

ONC. RANGEES • 0.6000 ONC. COL. ENTREE • 0.3000 ONC. COL. SORTIE • 0.3000

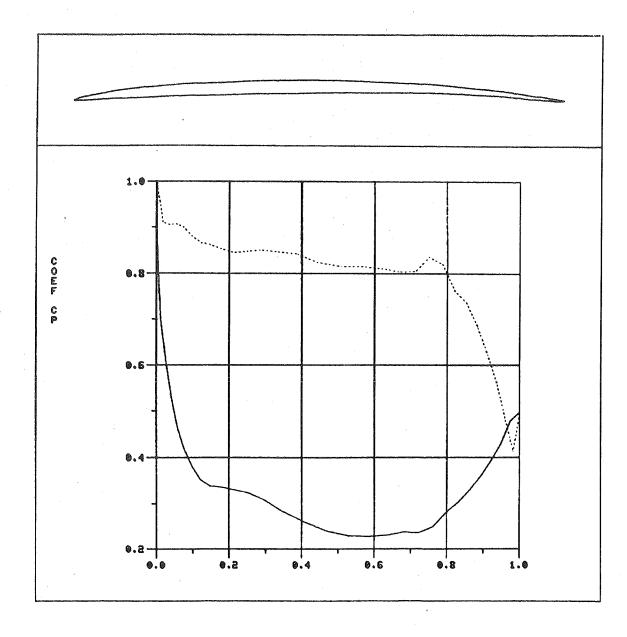


Fig. 21 Pressure Coefficient on Section 2

